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Nikos Mastorakis, Olga Martin, Gabriella Bognar, Siavash H. Sohrab,  
Daniel N. Riahi, Gilbert-Rainer Gillich**

**RECENT ADVANCES IN  
SIGNAL PROCESSING,  
COMPUTATIONAL GEOMETRY  
AND SYSTEMS THEORY**

- ◉ ***Proceedings of the 11<sup>th</sup> WSEAS International Conference on  
Signal Processing, Computational Geometry and Artificial Vision (ISCGAV '11)***
- ◉ ***Proceedings of the 11<sup>th</sup> WSEAS International Conference on  
Systems Theory and Scientific Computation (ISTASC '11)***



***Florence, Italy, August 23-25, 2011***

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**Editors:**

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**Preface**

This year the 11th WSEAS International Conference on SIGNAL PROCESSING, COMPUTATIONAL GEOMETRY and ARTIFICIAL VISION (ISCGAV '11) and the 11th WSEAS International Conference on SYSTEMS THEORY AND SCIENTIFIC COMPUTATION (ISTASC '11) were held in Florence, Italy, August 23-25, 2011. The conferences provided a platform to discuss filter design and structures, higher order spectrum analysis, cyclostationary signal analysis, speech production and perception, active noise reduction, machine vision, computed imaging, image filtering, computational geometry, robotics, virtual reality, soft computing, genetic algorithms, hybrid systems, game theory, real time systems, multilinear algebra, convergence problems, software development, functional languages, enumeration problems, communication protocols etc. with participants from all over the world, both from academia and from industry.

Their success is reflected in the papers received, with participants coming from several countries, allowing a real multinational multicultural exchange of experiences and ideas.

The accepted papers of these conferences are published in this Book that will be indexed by ISI. Please, check it: [www.worldses.org/indexes](http://www.worldses.org/indexes) as well as in the CD-ROM Proceedings. They will be also available in the E-Library of the WSEAS. The best papers will be also promoted in many Journals for further evaluation.

Conferences such as these can only succeed as a team effort, so the Editors want to thank the International Scientific Committee and the Reviewers for their excellent work in reviewing the papers as well as their invaluable input and advice.

The Editors



## Table of Contents

<b>Plenary Lecture 1: Robustness of Unbiased FIR Estimators against Outliers and Temporary Uncertainties</b> <i>Yuriy S. Shmaliy</i>	15
<b>Plenary Lecture 2: Diagnosis of Flexible Artificial Social Systems</b> <i>Calin I. Ciufudean</i>	16
<b>Plenary Lecture 3: Cooperated Output Regulation of Multi-Agent Systems: Theory and Applications</b> <i>Jie Huang</i>	17
<b>Plenary Lecture 4: Innovative Modeling Paradigms for Supporting Transition to Lean Healthcare</b> <i>Roberto Revetria</i>	18
<b>Synchronization of Identical New Chaotic Flows via Sliding Mode Controller and Linear Control</b> <i>Atefeh Saedian, Hassan Zarabadipour</i>	19
<b>Flux Reflection Model of Ferroresonant Circuit Realized Using Matlab/Simulink</b> <i>Kruno Milicevic, Dragan Vulin, Dusan Pejin</i>	25
<b>Impact of Initial Conditions on the Biggest Acceptable Integration Step Used for Solving the Lorenz's Equations</b> <i>Kruno Milicevic, Denis Pelin, Mihovil Milanovic</i>	31
<b>Simulation of Impact of a Wind Farm on the Grid Stability Using PowerWorld Simulator</b> <i>Dragan Vulin, Kruno Milicevic, Zdravko Burulic</i>	37
<b>Re-Examination of the Taper Models by Stochastic Differential Equations</b> <i>Petras Rupsys, Edmundas Petrauskas, Edmundas Bartkevicius, Romas Memgaudas</i>	43
<b>Grinding Circuit Control Using Programmable Logic Controllers</b> <i>Costea R.Claudiu, Silaghi Helga Maria, Rohde L. Ulrich, Silaghi A. Marius</i>	48
<b>Rough Sets Approach to the Classification Task with Modification of Decision Rules</b> <i>Andrzej Zolnierek, Marcin Majak</i>	53
<b>Modeling and Computer Spreadsheet Simulation of Real System – Mixing of Two Different Temperature Water Flows</b> <i>Stepan Hubalovsky</i>	57
<b>Modeling and Simulation of Real Experimental Device – Seven Storey Rectification Column</b> <i>Stepan Hubalovsky</i>	63

<b>Moral Hazard Resolved in Communication for S4n-Logic - Cyclic Communication Network Case</b> <i>Takashi Matsuhisa</i>	69
<b>Voice Signal's Noise Reduction Using Adaptive/Reconfigurable Filters for the Command of an Industrial Robot</b> <i>Claudia Moisa, Maria Helga Silaghi, Ulrich L. Rohde, Paul Silaghi, Andrei Silaghi, Marius A. Silaghi</i>	76
<b>Categorizing Cells in Phytoplankton Images</b> <i>Adas Gelzinis, Antanas Verikas, Marija Bacauskiene, Irina Olenina, Sergej Olenin</i>	82
<b>Optimum Microphone Array for Hands-Free Devices in a Car</b> <i>David Ayllon, Vanesa Benito-Olivares, Cosme Llerena-Aguilar</i>	88
<b>Neural Networks for Speech Separation for Binaural Hearing Aids</b> <i>Cosme Llerena-Aguilar, Roberto Gil-Pita, David Ayllon</i>	93
<b>Application of Neural Networks to Speech/Music/Noise Classification in Digital Hearing Aids</b> <i>Lorena Alvarez, Cosme Llerena, Enrique Alexandre</i>	97
<b>Improved Forecasting Considering Dynamic Properties within the Time Series of Customer Demands</b> <i>Bernd Scholz-Reiter, Mirko Kuck, Christian Toonen</i>	103
<b>Advanced User Authentication Process based on the Principles of Fractal Geometry</b> <i>Ivo Motyl, Roman Jasek</i>	109
<b>Pitch Detection in Pathological Voices Driven by Three Tailored Classical Pitch Detection Algorithms</b> <i>Cosme Llerena, Lorena Alvarez, David Ayllon</i>	113
<b>Unambiguous BOC Acquisition in Galileo Signal</b> <i>Wei-Lung Mao, Wei-Yin Zeng, Jyh Sheen, Wei-Ming Wang</i>	119
<b>Forecasting Neural Network-Based Fuzzy Time Series with Different Neural Network Models</b> <i>Memmedaga Memmedli, Ozer Ozdemir</i>	125
<b>Mathematical Model used for the Vibration Insulation within a Car</b> <i>Ionatan Popa, Ioan Enescu, Leonte Petric, Mihai Aleonte, Cosgarea Radu, Carol Ambrus, Eugenia Secara, Danut Vaduva</i>	130
<b>Data Exchange Software Module between AutoCAD and CATIA Environments</b> <i>Sever Alexandru Haba, Gheorghe Oancea, Anisor Nedelcu</i>	134
<b>Analysis of Ventilation System for a Microwave Assisted Drying Unit</b> <i>Adrian-Gabriel Ghiaus, Daniel Popescu, Calin Ciufudean</i>	138

<b>Study the Temperature Dependence of Elastic Modulus and Constants of Binary Alloys with Cubic Structure by Statistical Moment Method</b> <i>Thi Hoa Nguyen, Damian Valeriu, Calin Ciufudean</i>	144
<b>Modeling of Heat Transfer for an Ice Rink Track using Finite Elements</b> <i>Gelu Coman, Cristian Iosifescu, Calin Ciufudean, Valeriu Damian</i>	148
<b>A Novel Filter Design Method based on Greedy Search and Genetic Algorithms</b> <i>Paul Farago, Lelia Festila, Sorin Hintea, Peter Soser, Gabor Csipkes, Doris Csipkes, Calin Ciufudean</i>	152
<b>Wavelet Multi-Resolution Analysis of TPRD and RNSIC Input Current</b> <i>Constantin Filote, Calin Ciufudean, Ana Maria Cozgarea</i>	158
<b>A Simulation Study with Different Number of Observation Using Nonparametric Regression Splines</b> <i>Memmedaga Memmedli, Akhlitdin Nizamitdinov</i>	166
<b>Study of ADZT Properties for Spectral Analysis</b> <i>Vaclav Turon, Jan Janik, Radim Spetik, Pavel Sovka, Miroslav Vlcek</i>	171
<b>A Way to a New Multi-Spectral Transform</b> <i>Jan Janik, Vaclav Turon, Pavel Sovka, Radim Spetik, Miroslav Vlcek</i>	177
<b>On Oscillations Damping and Control for a Class of Affine Systems</b> <i>Virginia Ecaterina Oltean, Radu Dobrescu, Dan Popescu</i>	183
<b>Researches Concerning Risk Assessing Using Pareto Diagram for Design Process of Technological Processes</b> <i>Simona Duicu, Adela-Eliza Dumitrascu</i>	189
<b>Computing Efficient Solutions of Nonconvex Multi-Objective Problems via Scalarization</b> <i>Refail Kasimbeyli</i>	193
<b>Safety-First and Chance-Constrained Production Planning Models for Fish Farms</b> <i>Marius Radulescu, Constanta Zoie Radulescu, Magdalena Turek Rahoveanu</i>	199
<b>Improved Window Based On Cosine Hyperbolic Function</b> <i>M. Nouri, S. Sajjadi Ghaem Maghami</i>	205
<b>Sizing of a 3,000,000t Bulk Cargo Port through Discrete and Stochastic Simulation Integrated with Response Surface Methodology Techniques</b> <i>L. Cassettari, R. Mosca, R. Revetria, F. Rolando</i>	211
<b>Schroedinger Treatment and Wavefunction Engineering of Nanophotonic Device Functionality</b> <i>E. A. Anagnostakis</i>	217



<b>A Neural Network Approach for Land-Cover Change Detection in Multi-Temporal Multispectral Remote-Sensing Imagery</b>	221
<i>Victor-Emil Neagoe, Mihai Neghina, Mihai Datcu</i>	
<b>Emerging Technologies- the base for the Next Goal of Process Control - Risk and Hazard Control</b>	227
<i>Gheorghe Florea, Luiza Ocheana, Dan Popescu, Oana Rohat</i>	
<b>Superposition Principle applied to Natural Frequency Changes of a Beam with Multiple Cracks</b>	233
<i>Zeno-Iosif Praisach, Gilbert-Rainer Gillich, Pentru-Florin Minda, Nicoleta Gillich</i>	
<b>Study of Stress and Deformation in Elastomeric Isolation Systems Using the Finite Element Method</b>	239
<i>Claudiu Iavornic, Zeno-Iosif Praisach, Ovidiu Vasile, Gilber-Rainer Gillich, Vasile Iancu</i>	
<b>The Kinematic and Dynamic Analysis of the Crank Mechanism with SolidWorks Motion</b>	245
<i>Dorian Nedelcu, Marian-Dumitru Nedeloni, Daniel Daia</i>	
<b>Finite Element Analysis for Reactive and Dissipative Rectangular Muffler</b>	251
<i>Ovidiu Vasile, Nicoleta Gillich, Neagoe Laurentiu</i>	
<b>About Theory in Software Development</b>	256
<i>Javier Andrade, Juan Ares, Rafael Garcia, Maria-Aurora Martinez, Santiago Rodriguez, Sonia Suarez</i>	
<b>Collision Modeling of Small Dimensions Bearings Rolls</b>	262
<i>Manescu Tiberiu Jr., Manescu Stefan Tiberiu, Iacob-Mare Cornel, Avram Dan Silviu, Diana Ancas</i>	
<b>Subject-Independent Emotion Recognition from Facial Expressions using a Gabor Feature RBF Neural Classifier Trained with Virtual Samples Generated by Concurrent Self-Organizing Maps</b>	266
<i>Victor-Emil Neagoe, Adrian-Dumitru Ciotec</i>	
<b>Single and Double Layer Spiral Planar Inductors Optimisation with the Aid of Self-Organising Migrating Algorithm</b>	272
<i>Martin Pospisilik, Lukas Kouril, Ivo Motyl, Milan Adamek</i>	
<b>A Description of the Protein Structures by Evolutionary-Programmed Turing Machine</b>	278
<i>Lukas Kouril, Roman Jasek, Ivo Motyl</i>	
<b>Authors Index</b>	284

## Plenary Lecture 1

### Robustness of Unbiased FIR Estimators against Outliers and Temporary Uncertainties



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**Abstract:** In this lecture, we examine recently developed the  $p$ -shift finite impulse response (FIR) unbiased estimator (UE) intended for filtering ( $p = 0$ ),  $p$ -step prediction ( $p > 0$ ), and  $p$ -lag smoothing ( $p < 0$ ) of linear discrete time-varying state-space models. The estimator is investigated for robustness in Gaussian and non-Gaussian noise environments with outliers and temporary uncertainties in a comparison to the Kalman filter. The FIR UE algorithm is designed to have no requirements for noise and initial conditions and thus has strong engineering features. It is first presented in a batch form and then developed in the computationally efficient iterative Kalman-like one having the guaranteed bounded input/bounded output (BIBO) stability, unlike the Kalman filter. Owing to the imbedded BIBO stability and without any other special solutions, such as those used in robust filtering, the FIR UE is shown to have better robustness than the Kalman filter against the heavy-tailed noise and Gaussian noise with outliers. It is also shown to have a bit better robustness against temporary model uncertainties. Errors in the Kalman-like FIR UE are compared to the error bound (EB) specified via the noise power gain (NPG) serving as a limiter of errors in transversal estimators. We show that the EB specialized via the NPG in the three-sigma sense can also be useful in Kalman filtering. Examples of applications are taken from signal and image processing, clock synchronization, and control. Based upon these examples, we demonstrate that the Kalman-like FIR UE overperforms the Kalman filter one if the noise covariances and initial conditions are not known exactly, the noise constituents are not white sequences, and both the system and measurement noise components need to be filtered out. Otherwise, the errors are similar.

**Brief Biography of the Speaker:**

Dr. Yuriy S. Shmaliy is Full Professor in Electrical Engineering of the University of Guanajuato, Mexico, since 1999. He received the B.S., M.S., and Ph.D. degrees in 1974, 1976 and 1982, respectively, from the Kharkiv Aviation Institute, Ukraine. In 1992 he received the Dr.Sc. degree from the Kharkiv Railroad Institute. In March 1985, he joined the Kharkiv Military University. He serves as Full Professor beginning in 1986 and has a certificate of Professor from the Ukrainian Government in 1993. In 1993, he founded and, by 2001, had been a director-collaborator of the Scientific Center "Sichron" (Kharkiv, Ukraine) working in the field of precise time and frequency. His books Continuous-Time Signals (2006) and Continuous-Time Systems (2007) were published by Springer, New York. His book GPS-based Optimal FIR Filtering of Clock Models (2009) was published by Nova Science Publ., New York. He also contributed to several books with invited chapters. Dr. Shmaliy has 262 Journal and Conference papers and 80 patents. He is IEEE Fellow; was rewarded a title, Honorary Radio Engineer of the USSR, in 1991; was listed in Marquis Who's Who in the World in 1998; was listed in Outstanding People of the 20th Century, Cambridge, England in 1999; and was listed in The Contemporary Who's Who, American Bibliographical Institute, 2003. He is currently an Associate Editor of Recent Patents on Space Technology. He is a member of the Organizing and Program Committees of various Int. Symposia. His current interests include statistical signal processing, optimal estimation, and stochastic system theory.

## Plenary Lecture 2

### Diagnosis of Flexible Artificial Social Systems



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**Abstract:** A major consideration in designing a flexible manufacturing system is its availability. When a machine or any other hardware component of the system fails, the system reconfiguration is often less than perfect. It is shown that, if these imperfections constitute even a very small percent of all possible system faults, the availability of the system may be considerably reduced. A state is operational when its performance is better than a threshold value. In order to calculate the availability of a manufacturing system, its states (each corresponding to an acceptable system level) are determined. A system level is acceptable when its production capacity is satisfied. To analyze the system with failure/repair processes, Petri nets and Markov models are often used. As a manufacturing system includes a large number of components with failure/repair processes, the system-level discrete event model becomes computationally intractable. Our approach for the analysis of manufacturing systems assumes that the systems are decomposed in manufacturing cells. We focus on the diagnosis of the performance characteristics of workflows cells modelled with stochastic Petri nets (SPNs). This goal is achieved by using a new model for Artificial Social Systems (ASSs) behaviours, and by introducing equivalent transfer functions for SPNs.

ASSs exist in practically every multi-agent system, and play a major role in the performance and effectiveness chart of the agents. This is the reason why we introduce a suggestive model for ASSs. To model complex systems, such as flexible manufacturing ones, a class of Petri nets is developed, and briefly introduced.

This class allows representing the flow of physical resources and control information data of the Flexible Artificial Social Systems (FASSs) components. In the analysis of SPN we use simulations in respect to timing parameters in a generalized semi-Markov process (GSMP). By using existing results on perturbation analysis (e.g., delays in supply with raw materials, equipment failure, etc.), and by extending them to new physical interpretations, we address unbiased sensitivity estimators correlated with practical solutions in order to attenuate the perturbations.

The novelty of the approach is that the construction of large Markov chains is not required. Using a structural decomposition, the construction system is divided into cells. We can simplify the structure of the SPN using the presented approach, which is useful when we deal with complex Petri nets, and we need to simplify these structures (e.g. graphs) in order to analyze them properly. For each cell a Markov model was derived and the probability was determined for at least  $N_i$  working machines in cell  $i$ , for  $i = 1, 2, \dots, n$  and  $M_j$ , where  $j=1, \dots, m$ , working material handling system (MHS) at time  $t$ , where  $N_i$  and  $M_j$  satisfy the system production capacity requirements. Intuitively, bottleneck (BN) of a production line is understood as a machine that impedes the system performance in the strongest manner. Identification of BNs and their optimal capacity for avoiding the machines downtime is considered as one of the most important problems in manufacturing systems. Some examples illustrate this approach.

#### **Brief Biography of the Speaker:**

- Academic Positions: Assoc. Professor Ph.D. Eng., Dept. of Automatics and Computers, Faculty of Electrical Engineering and Computer Science, "Stefan cel Mare" University of Suceava, Romania.
- Fields of Scientific Activities: Discrete Event Systems, Complex Measurement Systems, Reliability and Diagnosis of Control Systems, Environmental Management.
- He published 8 books and over 140 scientific papers in conference proceedings and journals.
- Honor Member of the Romanian Society of Electrical & Control Engineering - Member of the Romanian Technical Experts Corp.
- Technical Expert of the Romanian Ministry of Justice.
- President of the Romanian Society of Electrical & Control Engineering, Suceava Branch.
- He is a member of the editorial boards of several international scientific journals and conferences of control systems and electric engineering science. He was designated chairmen at 21 international conferences.

## Plenary Lecture 3

### Cooperated Output Regulation of Multi-Agent Systems: Theory and Applications



#### Professor Jie Huang

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**Abstract:** Output regulation has been one of the central problems in control theory and applications for a few decades. This problem not only needs to guarantee the stability of the closed-loop system, but also enable the output of the closed-loop system to asymptotically track a class of reference inputs and reject a class of disturbances. Thus this problem is more challenging than the stabilization problem. This problem can precisely formulate many complex control problems such as the vibration suppression of high speed trains, vertical take-off and landing of airplanes in a carrier, and robot control and manipulation, and is thus of practical interests. So far the output regulation problem is mainly studied via a centralized control approach. As the world becomes more and more interconnected, more and more practical control problems such as the coordination of a group of mobile robots, and the formation of a group of unmanned flight vehicles must be described by a multi-agent system. Therefore, in this talk, we will describe a framework for handling the output regulation problem for a multi-agent system. The core of this framework includes the establishment of the concepts of the distributed observer, and the distributed internal model. On one hand, we will show that this framework will set a stage for solving the asymptotic tracking and disturbance rejection problem in an uncertain multi-agent system via a distributed control approach. On the other hand, we will show that this framework contains many control problems of multi-agent systems such as consensus, synchronization, and formation as special cases, thus leading to a unified solution to several different control problems of multi-agent systems.

#### Brief Biography of the Speaker:

Jie Huang studied Power Engineering at Fuzhou University from 1977 to 1979 and Circuits and Systems at Nanjing University of Science and Technology (NUST) from 1979 to 1982. He got his Master's degree from NUST in 1982 and was a faculty member there from 1982 to 1986. He completed his Ph.D. study in automatic control at the Johns Hopkins University in 1990 and subsequently held a post-doctoral fellow position there until July 1991. From August 1991 to July 1995, he worked in industry in USA. In September 1995, he joined the Department of Mechanical and Automation Engineering, the Chinese University of Hong Kong. He is now a professor and also the director of Applied Control and Computing Laboratory there. He served as a Science Advisor to the Leisure and Cultural Services Department of Hong Kong Special Administrative Region, and Honorary Advisor to Hong Kong Science Museum. His research interests include control theory and applications, robotics and automation, neural networks and systems biology, and guidance and control of flight vehicles. He authored two books and numerous papers. He received China State Natural Science Award, Class II, in 2010, Croucher Senior Research Fellowship award in 2006, and the best paper award (with Zhiyong Chen) of the Eighth International Conference on Control, Automation, Robotics, and Vision in 2004. He is IFAC Fellow and IEEE Fellow. Jie Huang is / was editor, associate editor, guest editor of several journals. He was Distinguished Lecturer of IEEE Control Systems Society from 2005 to 2008, member of the Board of Governors of IEEE Control Systems Society from 2006 to 2007. He served as general chair, program chair in numerous international Conferences.

## Plenary Lecture 4

### Innovative Modeling Paradigms for Supporting Transition to Lean Healthcare



#### Professor Roberto Revetria

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**Abstract:** Lean Healthcare, Kaizen and Six Sigma are rapidly transforming healthcare operations from 'new ideas' to a 'way of life', at the same time while the concepts of Lean are fairly straightforward, applying the tools to daily work can be counter-intuitive and thus require a credible model to be effectively applied. In traditional lean approach consultants take advantages from Value Stream Mapping, the adoption of 5-S and Visual Controls as well as batch reduction and cellular flow. Often these activities took very long time to be adopted mostly due to internal change resistance and lean implementation projects struggle for achieving their goals. In order to control budgets while ensuring proper level of assistance to their citizens a NHS requires modeling the various clinical processes (such as surgery, clinics, nursery) Modeling & Simulation Experts propose both very detailed and high fidelity discrete-events models and approximate Systems Dynamics micro-world. In the presenter experience none of such approaches definitively proven their superiority and a mixed approach has to be adopted. This talk presents an innovative approach where Systems Dynamics and State Transition Diagrams are integrated building a flexible and general model able to reproduce complex healthcare operations in a tradeoff between complexity and flexibility. The talk presents a complete case study applied to real life hospital. Methodology is presented and discussed.

#### **Brief Biography of the Speaker:**

He earned his degree in mechanical engineering at the University of Genoa and he completed his master thesis in Genoa Mass Transportation Company developing an automatic system integrating ANN (Artificial Neural Networks) and simulation with the ERP (Enterprise Resource Planning) for supporting purchasing activities. He had consulting experience in modeling applied to environmental management for the new Bosch plant facility TDI Common Rail Technology in construction near Bari. During his service in the Navy as officer, he was involved in the development of WSS&S (Weapon System Simulation & Service) Project. He completed his PhD in Mechanical Engineering in 2001 defending his Doctoral thesis on "Advances in Industrial Plant Management" by applying Artificial intelligence and Distributed Simulation to several Industrial Cases. Since 1998 is active in Distributed Simulation by moving US DoD HLA (High Level Architecture) Paradigm from Military to Industrial application. In 2000 he successfully led a research group first demonstrating practical application of HLA in not dedicated network involving a 8 International University Group. He is currently involved, as researcher, in the DIP of Genoa University, working on advanced modeling projects for Simulation/ERP integration and DSS/maintenance planning applied to industrial case studies (Contracting & Engineering and Retail companies). He is active in developing projects involving simulation with special attention to Distributed Discrete Event and Agent Based Continuous Simulation (SwarmSimulation Agents). He is teaching Modelling & Simulation, VV&A, Distributed Simulation (HLA), Project management in Master Courses Worldwide and he is teaching Industrial Plants Design in University of Genoa Masters' Courses. He is Professor in Mechanical Engineering and Logistics.

## Authors Index

Adamek, M.	272	Hintea, S.	152	Petric, L.	130
Aleonte, M.	130	Hubalovsky, S.	57, 63	Popa, I.	130
Alexandre, E.	97	Iancu, V.	239	Popescu, Dan.	183, 227
Alvarez, L.	97, 113	Iavornic, C.	239	Popescu, Dani.	138
Ambrus, C.	130	Iosifescu, C.	148	Pospisilik, M.	272
Anagnostakis, E. A.	217	Janik, J.	171, 177	Praisach, Z.-I.	233, 239
Ancas, D.	262	Jasek, R.	109, 278	Radu, C.	130
Andrade, J.	256	Kasimbeyli, R.	193	Radulescu, C. Z.	199
Ares, J.	256	Kouril, L.	272, 278	Radulescu, M.	199
Ayllon, D.	88, 93, 113	KuckV	103	Rahoveanu, M. T.	199
Bacauskiene, M.	82	Laurentiu, N.	251	Revetria, R.	211
Bartkevicius, E.	43	Llerena-Aguilar, C.	88, 93	Rodriguez, S.	256
Benito-Olivares, V.	88	Llerena-Aguilar, C.	97, 113	Rohat, O.	227
Burulic, Z.	37	Maghami, S. S. G.	205	Rohde, U.	76
Cassettari, L.	211	Majak, M.	53	Rolando, F.	211
Ciotec, A.-D.	266	Mao, W.-L.	119	Rupsys, P.	43
Ciufudean, C.	138, 144, 148	Martinez, M.-A.	256	Saedian, A.	19
Ciufudean, C.	152, 158	Matsuhisa, T.	69	Scholz-Reiter, B.	103
Claudiu, C. R.	48	Memgaudas, R.	43	Secara, E.	130
Coman, G.	148	Memmedli, M.	125, 166	Sheen, J.	119
Cornel, I.-M.	262	Milanovic, M.	31	Silaghi, A.	76
Cozgarea, A. M.	158	Milicevic, K.	25, 31, 37	Silaghi, A. M.	48, 76
Csipkes, D.	152	Minda, P.-F.	233	Silaghi, H. M.	48, 76
Csipkes, G.	152	Moisa, C.	76	Silaghi, P.	76
Daia, D.	245	Mosca, R.	211	Soser, P.	152
Damian, V.	148	Motyl, I.	109, 272, 278	Sovka, P.	171, 177
Dan Silviu, A.	262	Neagoe, V.-E.	221, 266	Spetik, R.	171, 177
Datcu, M.	221	Nedelcu, A.	134	Suarez, S.	256
Dobrescu, R.	183	Nedelcu, D.	245	Tiberiu Jr., M. S.	262
Duicu, S.	189	Nedeloni, M.-D.	245	Tiberiu, M. S.	262
Dumitrascu, A.-E.	189	Neghina, M.	221	Toonen, C.	103
Enescu, I.	130	Nguyen, T. H.	144	Turon, V.	171, 177
Farago, P.	152	Nizamitdinov, A.	166	Ulrich, R. L.	48
Festila, L.	152	Nouri, M.	205	Vaduva, D.	130
Filote, C.	158	Oancea, G.	134	Valeriu, D.	144
Florea, G.	227	Ocheana, L.	227	Vasile, O.	239, 251
Garcia, R.	256	Olenin, S.	82	Verikas, A.	82
Gelzinis, A.	82	Olenina, I.	82	Vlcek, M.	171, 177
Ghiaus, A.-G.	138	Oltean, V. E.	183	Vulin, D.	25, 37
Gillich, G.-R.	233, 239	Ozdemir, O.	125	Wang, W.-M.	119
Gillich, N.	233, 251	Pejin, D.	25	Zarabadipour, H.	19
Gil-Pita, R.	93	Pelin, D.	31	Zeng, W.-Y.	119
Haba, S. A.	134	Petrauskas, E.	43	Zolnierek, A.	53